

#### An Overview of Search Based Software Engineering Shin Yoo / CREST

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## Pair-programming



#### Outline

- Motivation
- Application Areas
  - Requirement Engineering / Test Suite Minimisation
  - Test Data Generation / Fault Localisation Techniques
- Future Directions

# Motivation: why optimise?

- Easier than building a perfect solution
- Computational power: fast, scalable
- Data-driven, quantitative
- Insightful; allows holistic observation of problem space

"The heavy use of computer analysis has pushed the game itself in new directions. The machine doesn't care about style or patterns or hundreds of years of established theory. It is entirely free of prejudice and doctrine and this has contributed to the development of players who are almost as free of dogma as the machines with which they train. (...) Although we still require a strong measure of intuition and logic to play well, humans today are starting to play more like computers."

- Gary Kasparov, "The Chess Master and the Computer"

# **Application Areas**

Requirement Analysis Model Checking Test Data Generation Regression Testing Refactoring Software Design Tools Fault Localisation Agent-based System Automated Patch Generation Project Management

... still expanding with many more to come

# **Application Areas**

#### Tier 1

Combinatorial problems in SE context

Requir**SetherotvAn**alysis Re**greissitin**a**Testi**ng Proj**&inAøankigeg**nent Tier 2

Problems that are

specific to SE **Test Data Generation** Software Design Tools Model Checking **Agent-based System** Refactoring Fault Localisation **Automated Patch Generation** 

# Case Study: Requirements

- \* "What is the most cost-effective subset of software requirements to be included in the next version?"
- \* "What is the most efficient release schedule?"
- \* "Are customers treated fairly?"

#### Requirements: selection

- Underlying problem structure: knapsack problem
  - Requirements value: based on customer input, customer value, expected revenue, etc
  - Requirement cost: development cost, time, etc
- \* Goal: *minimise* cost, *maximise* value

#### **Requirements: selection**



#### Requirements: fairness



30% resource limitation

50% resource limitation

70% resource limitation

#### Case Study: Test Suite Minimisation

- \* The Problem: Your regression test suite is too large.
- The Idea: There must be some redundant test cases.
- The Solution: Minimise (or reduce) your regression test suite by removing all the redundant tests.

#### Minimisation

Seeks to reduce the size of test suites while satisfying test adequacy goals



#### Minimisation

	r0	r1	r2	•••
t0	1	1	0	
t1	0	1	0	
t2	0	0	1	
•••				

Things to tick off (branches, statements, DU-paths, etc)

Your tests

Usually the information you need can be expressed as a matrix.

#### Minimisation

- \* This is a set cover problem, which is NP-complete.
- Greedy heuristic is known to be within bounded error from the optimal solution.
- \* Problem solved?

Test Case	Program Blocks							Timo			
	1	2	3	4	5	6	7	8	9	10	mile
T1	x	x	x	x	x	x	x	x			4
T2	x	x		x	x	x	x	x	x	x	5
T3	x	x	x						x		3
T4	x	x	x	x	x						3

Single Objective

Choose test case with highest block per time ratio as the next one

> 1) T1 (ratio = 2.0) 2) T2 (ratio = 2 / 5 = 0.4)

 $\therefore$  {T1, T2} (takes 9 hours)

"But we only have 7 hours...?"





Faster Fault Finding at Google Using Multi-Objective Regression Test Optimisation Shin Yoo, Robert Nilsson, and Mark Harman, FSE2011 (Supported by Google Research Award: MORTO)

cone coverage

CL 15280453

#### Benefits of Abstraction



#### Benefits of Abstraction

- Analytic Hierarchical Process: first used in Requirement Engineering, now also used for regression test prioritisation
- Average Percentage of Fault Detection: metric devised for regression test prioritisation, now being recast for prioritisation or requirements

# Search-Based Testing

- Fitness function for branch coverage = [approximation level] + normalise([branch distance])
- \* For a target branch and a given path that does not cover the target:
  - Approximation level: number of <u>un-penetrated nesting levels</u> surrounding the target
  - Branch distance: how close the input came to satisfying the condition of <u>the last predicate that went wrong</u>

#### **Branch Distance**

- If you want to satisfy the predicate x == y, you convert this to branch distance of b = |x - y| and seek the values of x and y that minimise b to 0
  - \* then you will have x and y that are equal to each other
- If you want to satisfy the predicate y >= x, you convert this to branch distance of b = x - y + K and seek the values of x and y that minimise b to 0
  - \* then you will have y that is larger than x by K
- \* Normalise **b** to **1 1.001<sup>(-b)</sup>**

#### Branch Distance

Predicate	f	minimise until
a > b	b - a + K	f < 0
a >= b	b - a + K	f <= 0
a < b	a - b + K	f < 0
a <= b	a - b + K	f <= 0
a == b	la-bl	f == 0
a != b	-la-bl	f < 0

B. Korel, "Automated software test data generation," IEEE Trans. Softw. Eng., vol. 16, pp. 870–879, August 1990.

#### **Fitness Function**



Test input (a, b, c), K = 1

# An Example of Search Algorithm

- Hill Climbing
  - start with random value
  - calculate fitness
  - \* check out <u>neighbours</u>
  - if there is a fitter neighbour, move
  - repeat until succeed



if(c == 4)

False

True

Target

#### Case Study: Fault Localisation



## Case Study: Fault Localisation



- \* Green: GP outperforms the other.
- Orange: GP exactly matches the other.
- \* Red: The other outperforms GP.

4 Unix tools w/ 92 faults: 20 for training, 72 for evaluation.

# The most effective way to do it, is to do it.

- GP provides a structured, automated way of doing iterative design.
- \* It can cope with a much diverse spectra and other meta-data.
- GP can evolve a technique that suits your project.



# **Optimisation Techniques**

- \* Genetic Algorithm: versatile, most popular (cool factor?)
- Hill climbing, Simulated Annealing: often as competitive as, or even better than, GA
- Exact methods: least widely used scalable? flexible? multiobjectiveness?

#### **Future Directions**

# Multi-Objective Paradigm

- Already explored in testing and requirements, others to follow
  - Copes with complex constraints
  - Works well when there are multiple surrogate fitness

# Interactivity

- Relatively unexplored due to the high cost of human input
  - Eliciting human knowledge
  - Resolving ambiguities that are hard to quantise
  - Using unconventional interfaces



# Getting Fuzzier!

- \* Get out of the classical combinatorial problem box
- \* NLP, Information Theory, Probabilistic Modelling, etc

## Kasparov's Advanced Chess

- Competition between teams consist of human + chess software
- \* It looks very similar to our goal in a lot of ways...

# Kasparov's Advanced Chess

- \* "..being able to access a database of a few million games meant that we didn't have to strain our memories nearly as much in the opening.."
- "Having a computer partner also meant never having to worry about making a tactical blunder."
- "Weak human + machine + better process was superior to a strong computer alone and, more remarkably, superior to a strong human + machine + inferior process."

#### The Ultimate Goal

 Our final goal is not to replace human decision making process; it is to aid the process with an unbiased alternative and an insight into the problem structure

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