

Automated Test Data Generation for Coverage: Haven't We Solved This Problem Yet?

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Lately two very different automated test data generation techniques have gained a lot of attention:

- Search based testing (e.g. EvoTest www.evotest.eu, 3 year project worth \$4m)
- Dynamic symbolic execution (e.g. Pex, CUTE, CREST)

But,

- How effective are concolic and search based test data generation for real world programs?
- What is the relative efficiency of both approaches?
- Which types of program structure does each technique fail to cover?

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We transform the testing problem into an optimization problem; the assumption is that comparing two potential solutions is easier than generating a correct solution from scratch.

Example	Candidate Solutions
<pre>void testme(int a, int b) { if(a * b > 100) //target } Branch Distance Function: if(100 - (a * b) < 0) return 0; else return (100 - (a * b)) + constant;</pre>	<ul style="list-style-type: none"> • a = 0, b = 10 random start

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<p>Branch Distance Function:</p> <pre>if(100 - (a * b) < 0) return 0; else return (100 - (a * b)) + constant;</pre>	

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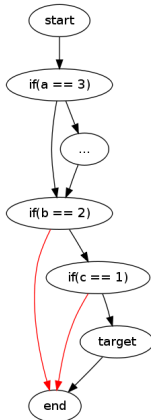
Answers

Summary

In search based testing we are not concerned about which path leads to the target. The path taken up to a target is an emergent property of the search process.

```
void testme(int a, int b, int c)
{
    if(a == 3)
    {
        ...
    }

    if(b == 2)
        if(c == 1)
            //target
}
}
```



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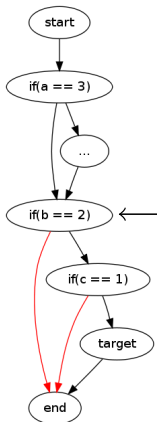
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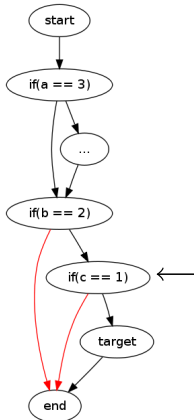
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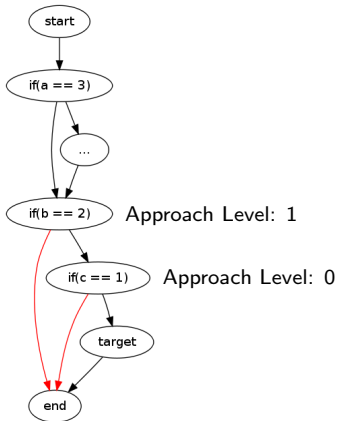
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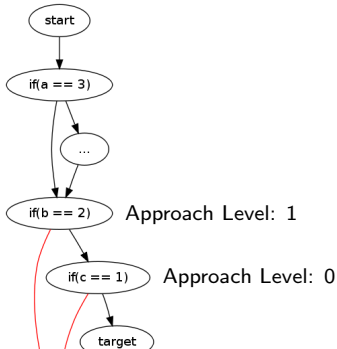
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```



Fitness Function:

Approach Level + normalized(Branch Distance)

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AUSTIN: Cover all goals (*i.e.* edges in a control flow graph)

- Execute program with a concrete input vector
- Symbolically execute concrete path taken by said input in parallel
- When execution follows an infeasible path w.r.t. current goal
 - Apply a hill climb algorithm to solve arithmetic constraints
 - Apply custom pointer rules to solve constraint over memory locations

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The term concolic stands for **concrete** execution with **symbolic** execution. It is similar to dynamic symbolic execution:

- Explore all feasible execution paths
- Execute program with a concrete input vector
- Symbolically execute concrete path taken by said input in parallel
- Use concrete values to simplify symbolic expressions when necessary (*i.e.* regard them as constant values)

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Suppose you want to find input values for a and b to traverse the path to the target.

Example	Concrete Values	Path Condition
<pre>void testme(int a, int b) { if(a * b > 100) //target }</pre>	$a = -10, b = 50$	$(a_0 * b_0) \leq 100$

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But your constraint solver cannot handle non-linear constraints.

Example	Concrete Values	Path Condition
<pre>void testme(int a, int b) { if(a * b > 100) //target }</pre>	<p>a = -10, b = 50</p>	<p>$(a_0 * b_0) > 100$</p>

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Simplify the path condition to make it amenable to your constraint solver.

Example	Concrete Values	Path Condition
<pre>void testme(int a, int b) { if(a * b > 100) //target }</pre>	<p>a = -10, b = 50</p>	<p>$(\textit{constant} * b_0) > 100$</p>

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Substitute runtime values for symbolic expressions when necessary.

Example	Concrete Values	Path Condition
<pre>void testme(int a, int b) { if(a * b > 100) //target }</pre>	<p>a = -10, b = 50</p>	<p>$(-10 * b_0) > 100$</p>

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You can now use your constraint solver to find an input value for b . You leave the value of a unchanged, and thus execution will traverse your desired path.

Example	Concrete Values	Path Condition
<pre>void testme(int a, int b) { if(a * b > 100) //target }</pre>	$a = -10, b = -11$	$(-10 * b_0) > 100$

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CUTE: Explore all feasible execution paths

- Execute the program with a concrete input vector (all inputs set to zero, all pointers set to NULL)
- Simplify symbolic expressions with runtime values
- Invert last constraint in path condition (and use backtracktracking) to drive successive executions down different program paths
- Use `lp_solve` to obtain concrete input values
- Apply custom pointer rules to solve constraint over memory locations

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- Use CIL to simplify C code into more amenable form
 - Constraints are either of pointer or arithmetic type
- Represent each memory location reachable from the function under test with a symbolic variable
- Collect all constraints over memory locations from symbolic path condition
- Form equivalence classes of symbolic variables, based on the = operators in the path condition
- Construct an undirected graph whose nodes are above equivalence classes. Edges represent inequalities, defined by the \neq operators in the path condition

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Example	Concrete Values	Symbolic States	Path Condition
<pre>typedef struct item{ struct item* next; } void testme(item* p, item* q) { if(p != NULL) if(p->next == q) //target } </pre>	<p>$p=NULL, q=NULL$</p>	<p>$p = p_0, q = q_0$</p>	

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Solve: $p_0 \neq NULL$

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<pre>typedef struct item{ struct item* next; } void testme(item* p, item* q) { if(p != NULL) if(p->next == q) //target }</pre>	$p=0x\dots, q=NULL$	$p = p_0, q = q_0, next = next_0$	$p_0 \neq NULL$

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Example	Equivalence Graph
<pre>typedef struct item{ struct item* next; } void testme(item* p, item* q) { if(p != NULL) if(p->next == q) //target }</pre>	<pre> graph LR p0((p_0)) --- null(({NULL})) next0(({next_0, q_0})) </pre>

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- Use default settings for each tool
- Generate test driver for each (non-trivial) function, for both tools without specifying any preconditions
- Instrument the source file containing function under test for each tool (other source files remain un-instrumented)
- Limit each tool to a maximum wall clock runtime of 2min for each function
- Repeat experiments 30 times for each tool

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We used a total of 169,161 pre-processed lines of C code contained within five open-source programs to compare CUTE against AUSTIN.

Test Object	Lines of Code	Functions		Branches	
		Total	Tested	Total	Tested
libogg	2,552	68	33	290	284
plot2d	6,062	35	35	1,524	1,522
time	5,503	12	10	202	198
vi	81,572	474	405	8,950	8,372
zile	73,472	446	340	3,630	3,348
Total	169,161	1,035	823	14,596	14,084

Functions Total: total number of functions in the program

Functions Tested: number of functions that were testable by the tools

Branches Total: total number of branches in the program

Branches Tested: number of branches contained within the tested functions

Branch Coverage of Function Under Test Only

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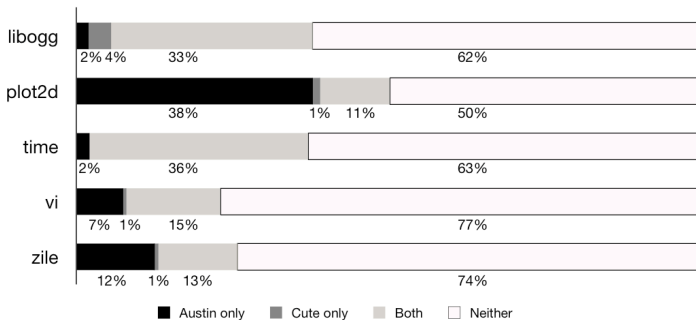
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Branch Coverage of Function Under Test And Interprocedurally

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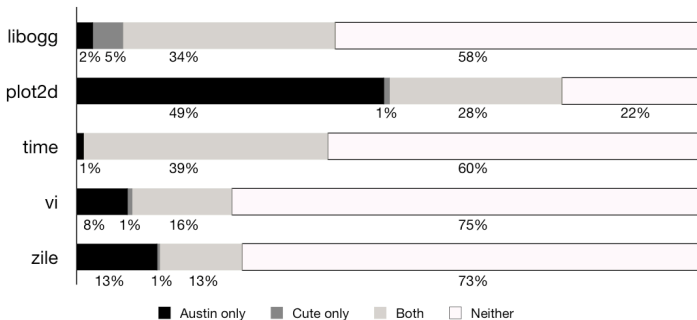
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Branch Coverage of Functions CUTE Can Handle Only

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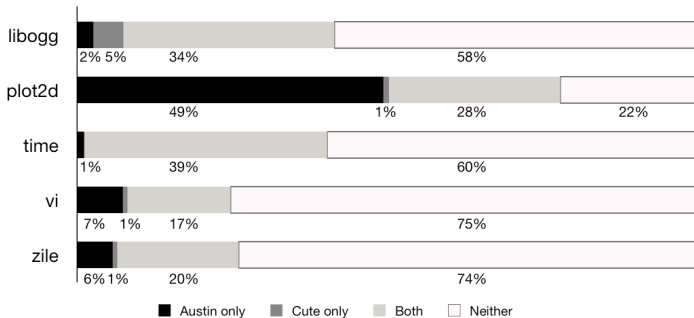
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Efficiency Measured on Sample Functions

Function	CUTE			AUSTIN		
	Time (s)	Branches covered FUT	(Inter-procedural)	Time (s)	Branches covered FUT	(Inter-procedural)
ogg_stream_clear	0.84	7/8	(8)/(8)	134.75	5/8	(7)/(8)
oggpack_read	0.24	2/14	(2)/(14)	0.18	2/14	(2)/(14)
CPLLOT_BYTE_MTX_Fill	131.25	4/4	(4)/(8)	130.05	1/4	(1)/(8)
CPLLOT_DrawDashedLine	130.43	13/56	(13)/(56)	130.40	37/56	(37)/(56)
CPLLOT_DrawPoint	0.51	13/16	(13)/(16)	131.82	13/16	(13)/(16)
reuse_end	0.42	4/6	(4)/(6)	131.84	5/6	(5)/(6)
_compile	2.11	26/348	(26)/(348)	34.14	24/348	(24)/(348)
exitex	146.47	1/4	(1)/(4)	0.22	1/4	(1)/(4)
main	0.45	0/152	(0)/(174)	0.31	0/152	(0)/(174)
plod	1.58	18/174	(18)/(174)	137.17	18/174	(18)/(174)
pofix	0.41	1/4	(1)/(4)	135.08	1/4	(1)/(4)
vappend	0.53	6/134	(6)/(426)	0.26	6/134	(6)/(426)
vgetline	0.81	3/220	(3)/(228)	0.26	3/220	(3)/(228)
vmain	0.27	3/404	(3)/(480)	0.30	3/404	(3)/(480)
vmove	0.79	3/30	(3)/(30)	0.24	3/30	(3)/(30)
vnpins	0.22	2/6	(2)/(108)	0.25	2/6	(2)/(108)
vputchar	0.20	4/148	(4)/(212)	0.25	4/148	(4)/(212)
astr_rfind_cstr	0.45	2/6	(2)/(6)	0.17	2/6	(2)/(6)
check_case	0.38	1/6	(1)/(6)	130.49	6/6	(6)/(6)
expand_path	0.37	0/82	(1)/(84)	0.16	0/82	(1)/(84)
find_window	0.40	1/20	(1)/(20)	131.40	1/20	(1)/(20)
line_beginning_position	0.27	0/8	(0)/(8)	0.18	0/8	(0)/(8)
setcase_word	0.31	0/40	(0)/(74)	0.18	0/40	(0)/(74)
Total	419.71	114/1890	116/2494	1230.10	137/1890	140/2494

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RQ 1: How effective are concolic and search based test data generation for real world programs?

Not very. For all test subjects both tools achieve less than 50% C/DC coverage.

RQ 2: What is the relative efficiency of each individual approach?

Overall one cannot say either CUTE or AUSTIN is more efficient. When run on code which is amenable to concolic testing and CUTE's implementation of it, CUTE is more efficient than AUSTIN.

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RQ 3: Which types of program structure did each technique fail to cover?

Both tools performed badly for:

- functions that use pointers without checking if they have been initialized.
- functions that contain a void pointer, function pointer, or string input.
- programs which take another process or program as input.
- variable argument length functions.

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- Its unbounded depth first search often gets stuck in loops
- Implementation of pointer solving rules does not precisely follow their description
- Cannot handle floating type inputs
- Cannot test code containing bitfields

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Testing

Concolic Testing

Pointers in
CUTE and
AUSTIN

Empirical
Study

Experimental
Setup

Test Subjects

Results

Answers

Summary

- Its unbounded depth first search often gets stuck in loops
- Implementation of pointer solving rules does not precisely follow their description
- Cannot handle floating type inputs
- Cannot test code containing bitfields
- Its symbolic engine is not powerful enough for a range of software

Example	Symbolic State
<pre>void testme(int a, int b){ int x = (int)(a / b); int y = b << 1; if(x == y) //target }</pre>	$a = a_0, b = b_0, x = \text{constant}, y = \text{constant}$

Haven't We
Solved This
Problem Yet?

Lakhotia et al.

Outline

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- Does not use any input domain reduction; very large search space can render the hill climb ineffective, leading to violation of 2min timeout
- Does not easily discover links between input variables (e.g. `argc,argv`)
- Does not use any data flow information, thus search gets easily stuck on plateaus (equal to flag problem)
- Pointer constraints are only solved if they appear in critical branching nodes; *i.e.* constraints which influence critical branching nodes remain unsolved

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```
int foo(int * p) {
    if( p != NULL)
        return 1;
    else
        return 0;
}

void testme(int* p) {
    if( ! foo(p) ) return;

    //unreachable for AUSTIN
}
```

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- Cannot handle strings automatically (when is a `char*` a null terminated string, when an array of chars, and when a pointer to a single character?)
- Cannot handle a number of `stdlib` functions, e.g. `memset`, `memmove`, `memcpy`, `calloc`

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- Cannot handle strings automatically (when is a `char*` a null terminated string, when an array of chars, and when a pointer to a single character?)
- Cannot handle a number of `stdlib` functions, e.g. `memset`, `memmove`, `memcpy`, `calloc`
- Cannot handle union structures correctly, lacks analysis of which member is used

```
union nums
{
    char ch;
    int i;
    long l;
};
```

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- Cannot recover from segmentation faults
 - Cannot infer preconditions to functions
- Cannot handle void pointers
- Cannot handle function pointers
- Cannot handle variable argument length functions

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Summary

Use search to

- solve constraints over floating point inputs
- handle black box function calls

Use dynamic symbolic execution to

- prune infeasible paths
- reduce the search space
- solve constraints whenever possible

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```
void foo(int* a, int* b, int* c, int* d)
{
    if(a != null)
        if(a == b)
            if(c == d)
                if(a == c)
                    assert( false );
}
```