

A Theoretical & Empirical Analysis of Evolutionary Testing and Hill Climbing for Structural Test Data Generation

ISSTA July 2007



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ISSTA: Empirical and Theoretical Search Based Testing

Which Search Technique: Global or Local?



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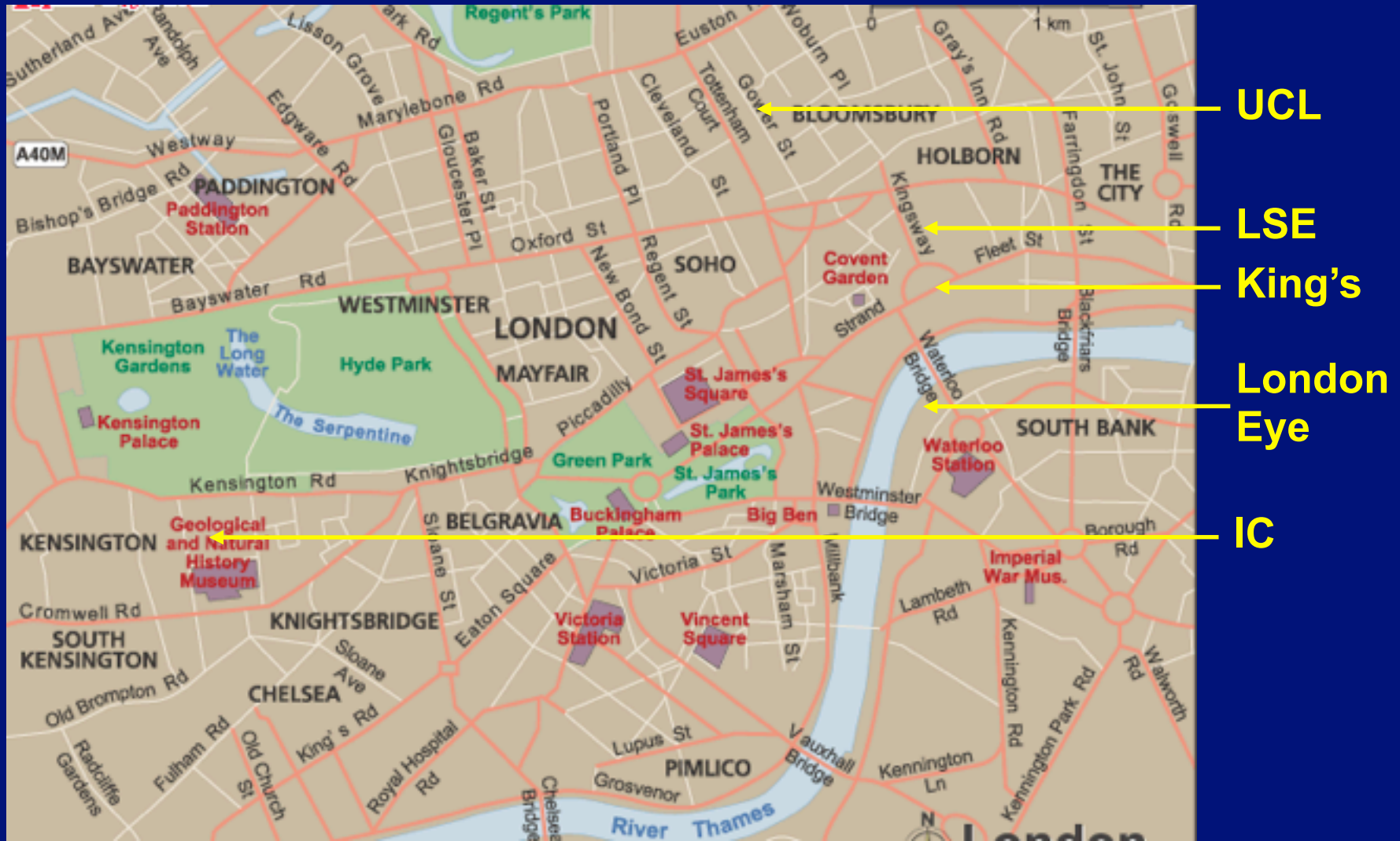
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Author order is alphabetical

Where is King's College London?



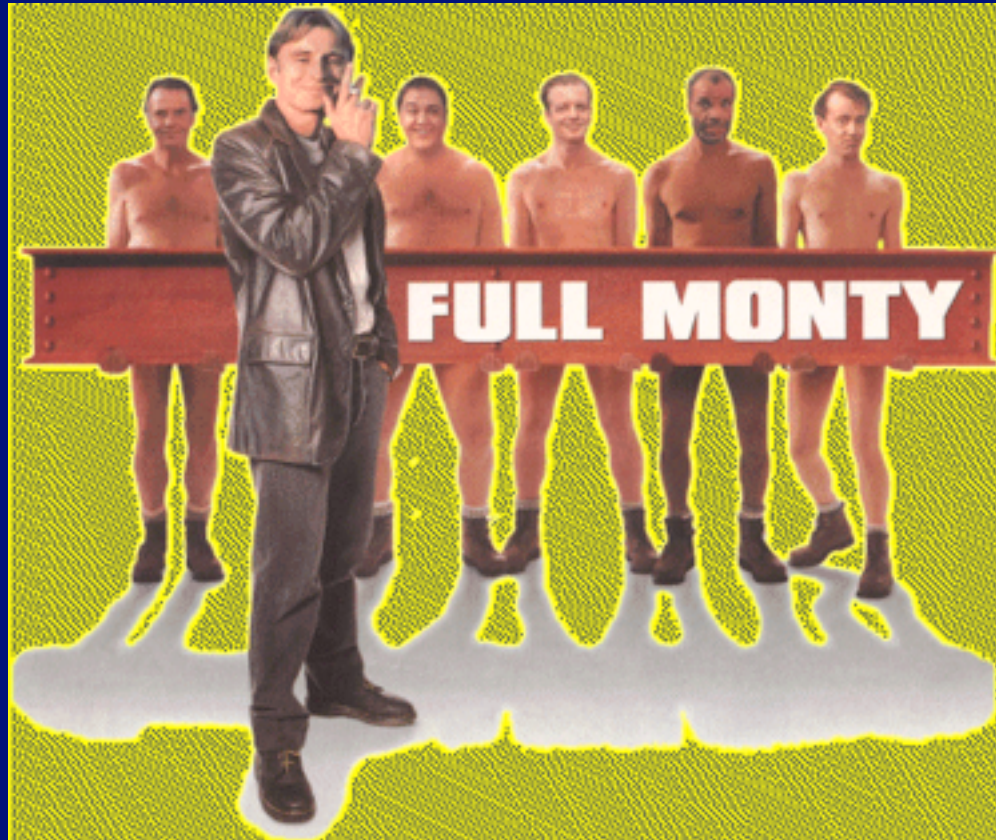
Where is Sheffield University?



Sheffield

London

No Full Monty Joke



No Full Monty Joke

Sorry



Overview

Search Based Testing

Local: Hill Climbing using Alternating variable method

Global: Genetic Algorithms

Theoretical foundations

Schemas

Royal Roads

Empirical study

Implications

What is SBT

In Search based testing we apply search techniques to search large input spaces, guided by a fitness function.

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Genetic Algorithms, Hill climbing, Simulated Annealing, Random, Tabu Search, Estimation of Distribution Algorithms, Particle Swarm Optimization

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Structural Testing

Focus on branch testing

Most widely studied

So ready for some more in depth analysis

Other Search Based Testing Applications

Temporal Wegener et al.

Coverage Pargass & Harrold, Xanthakis et al., McMinn, Harman, Michael et al, Sthamer, Jones ...

Functional Wegener et al.

Regression Rothermel et al., Woolcott et al., Yoo and Harman,...

Interaction Cohen et al. Bryce, Colbourn

Exception Tracey and Clark

Stress Briand et al., Antoniol, Di Penta

Robustness Shultz et al.

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Two algorithms:

Hill Climbing, using Korel's alternating variable method

Genetic Algorithms, using DaimlerChrysler approach

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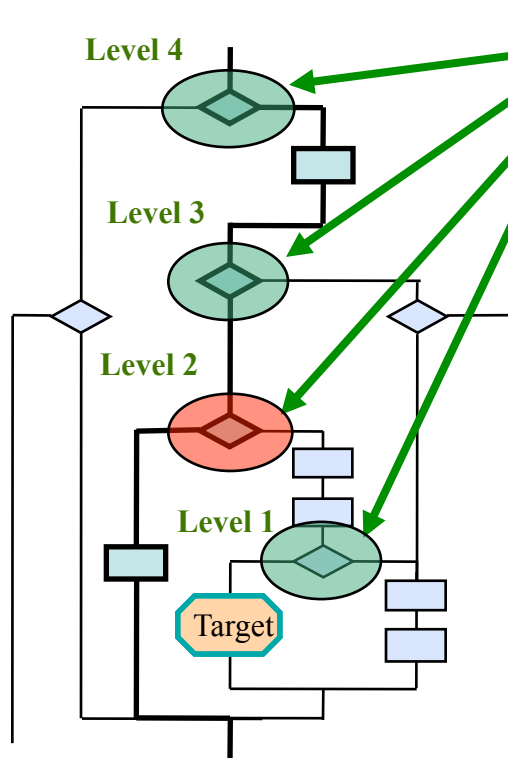
Two algorithms:

Hill Climbing, using Korel's alternating variable method

Genetic Algorithms, using DaimlerChrysler approach

... and Random Search

Fitness Computation



1. Approximation level

Identify relevant branching statements using control dependence

Evaluation of predicate in a branching condition

if $A = B$ **Local_Distance** = $|A - B|$

Fitness = **Approximation_Level** + **Local_Distance**

Alternating Variable Method

The alternating variable method is
hill climbing plus accelerated moves

Near Neighbour?

One small increase
One small decrease } For some input variable

Method:

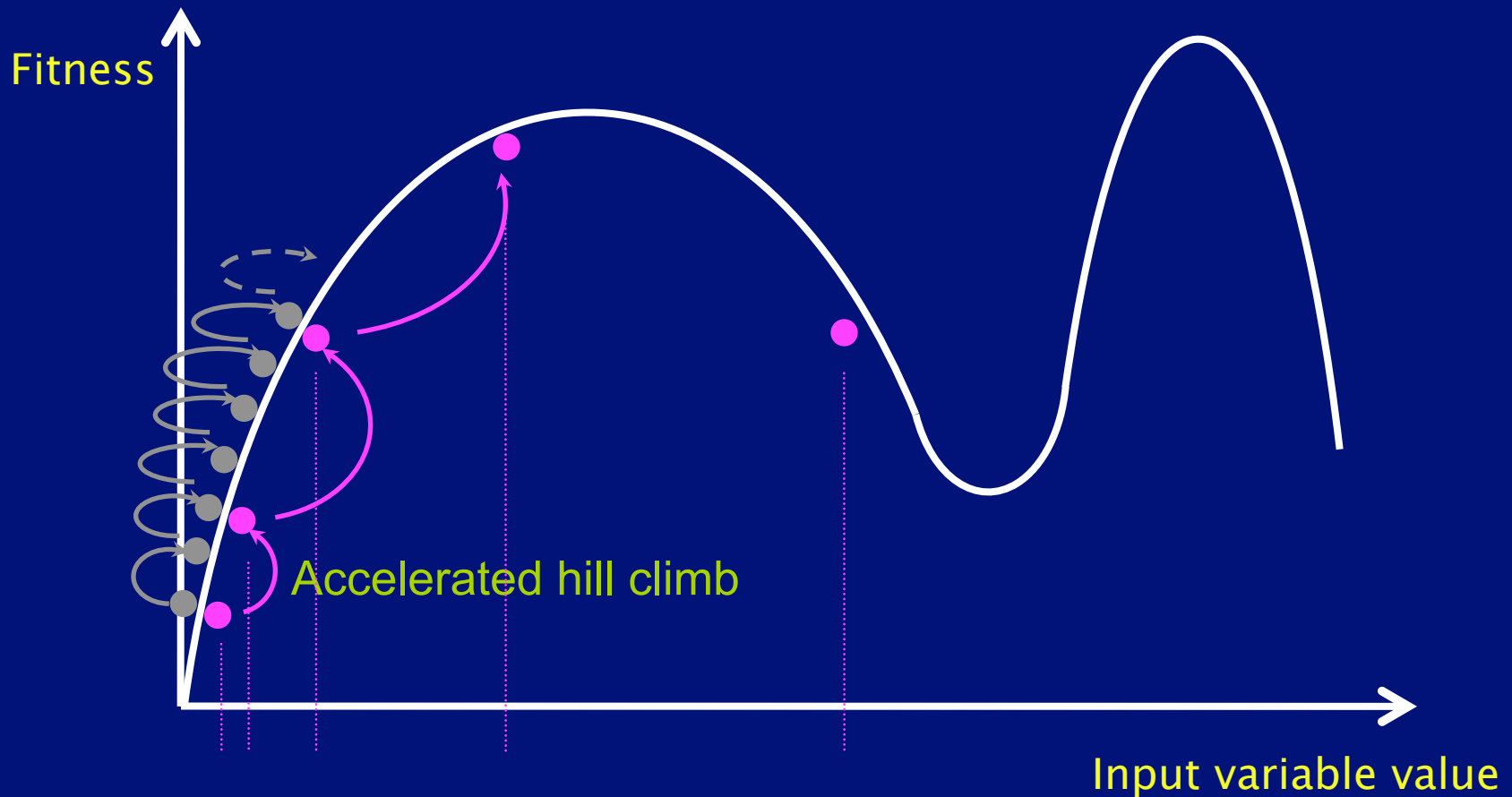
Cycle through input variables one at a time:

probe moves move to near neighbour:

If probing works, make accelerated pattern moves

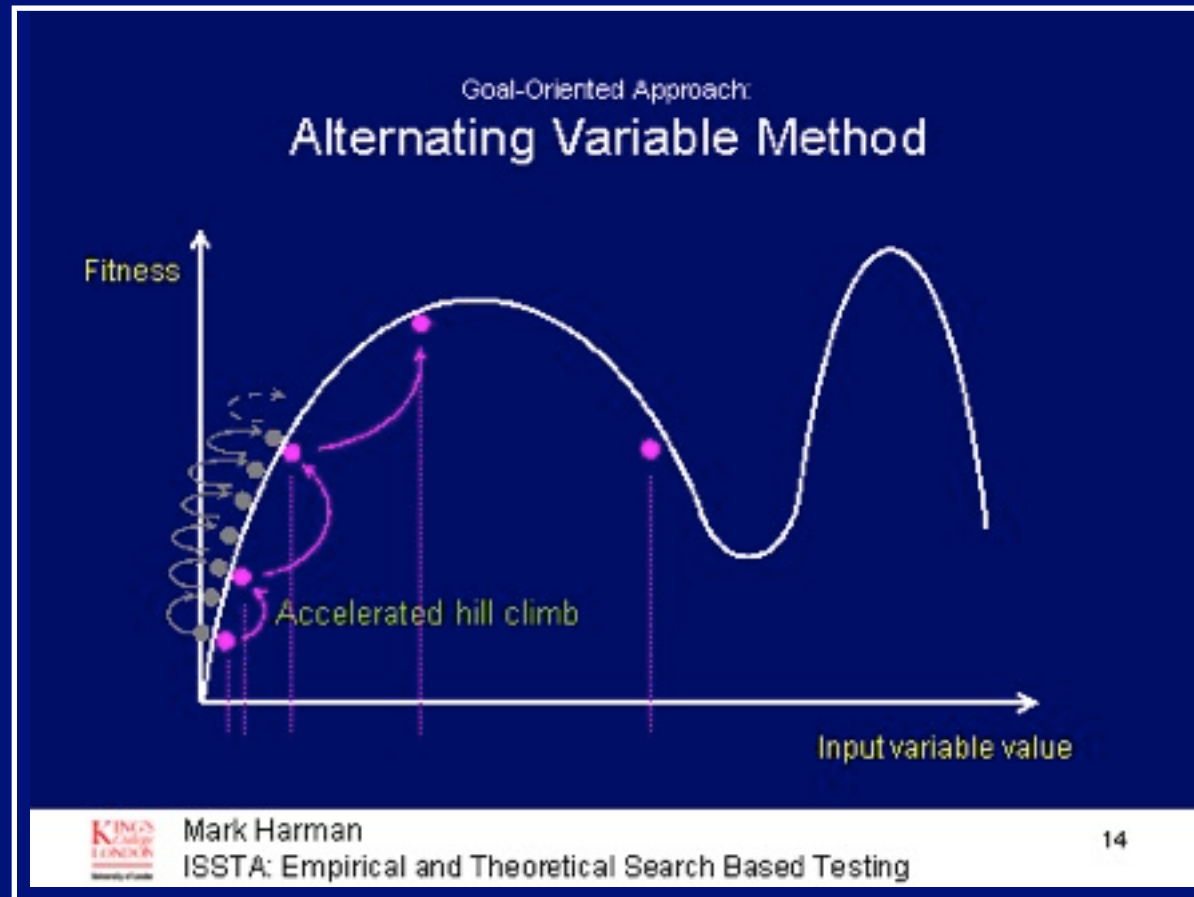
Until no improvement on any variable

Goal-Oriented Approach:
Alternating Variable Method




Hill Climbing ↔ Steepest Descent

Hill Climbing ↔ Steepest Descent



Alternating Variable Method Example

```
void example(int a, int b, int c) {  
    if (a == 0) {  
        ...  
    }  
  
    if (b == 0) {  
        if (c == 0) {  
            // target  
        }  
    }  
}
```



**Random start: a=10 b=20
c=30**

Case a :-

**Probe move has
no effect**

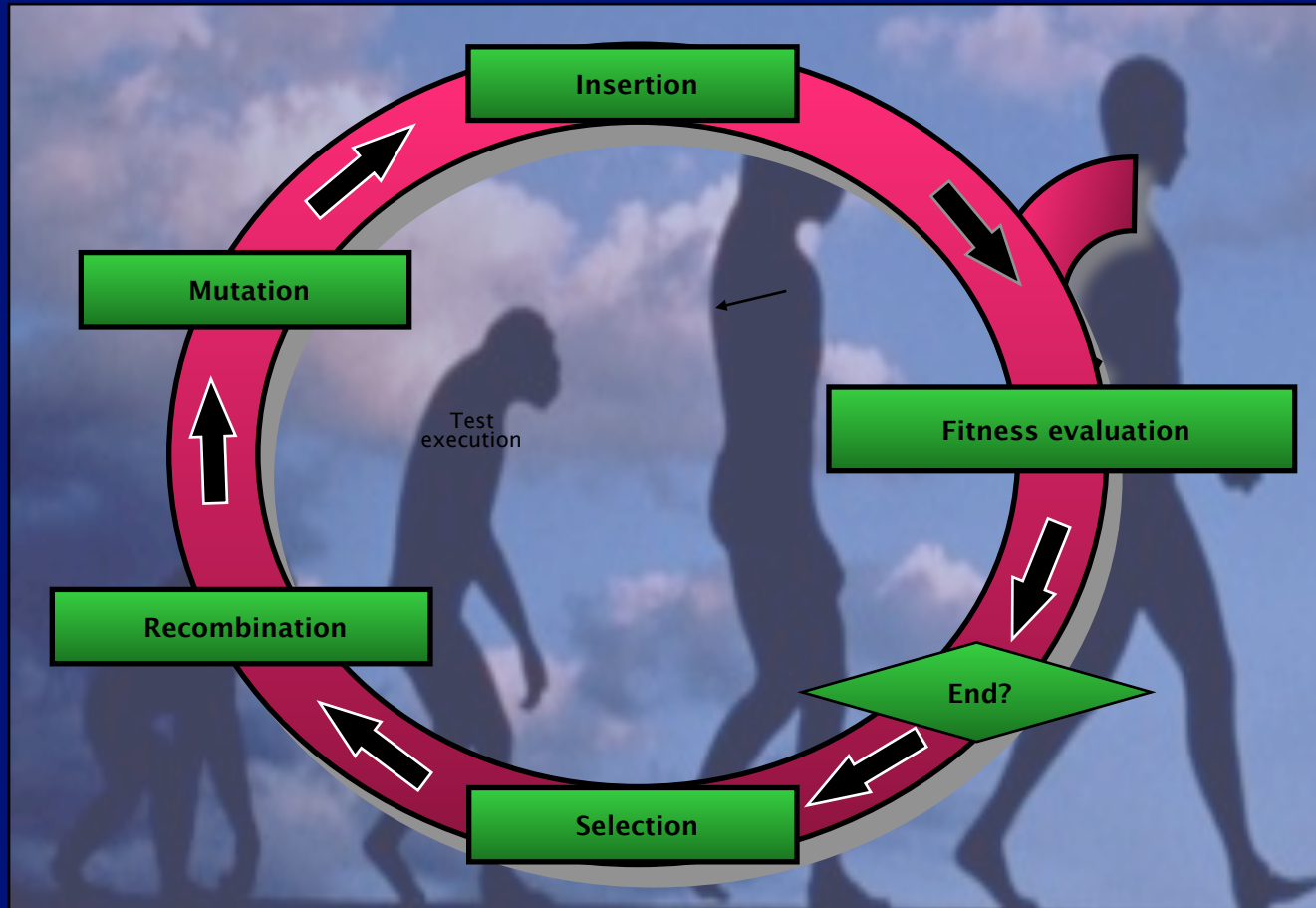
Case b :-

**Decrease probe
improves**

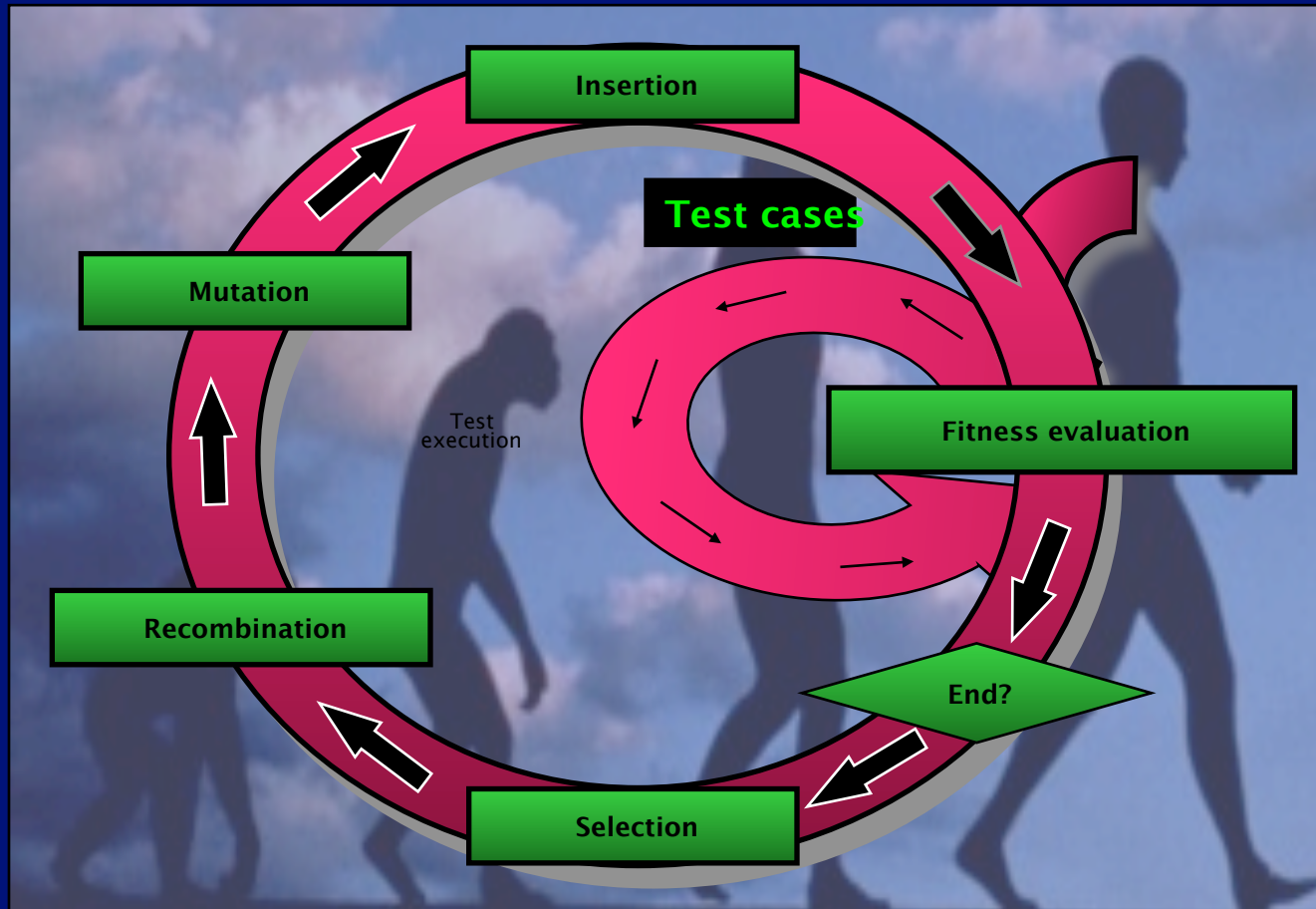
**So accelerate
until b=0**

Case c :-

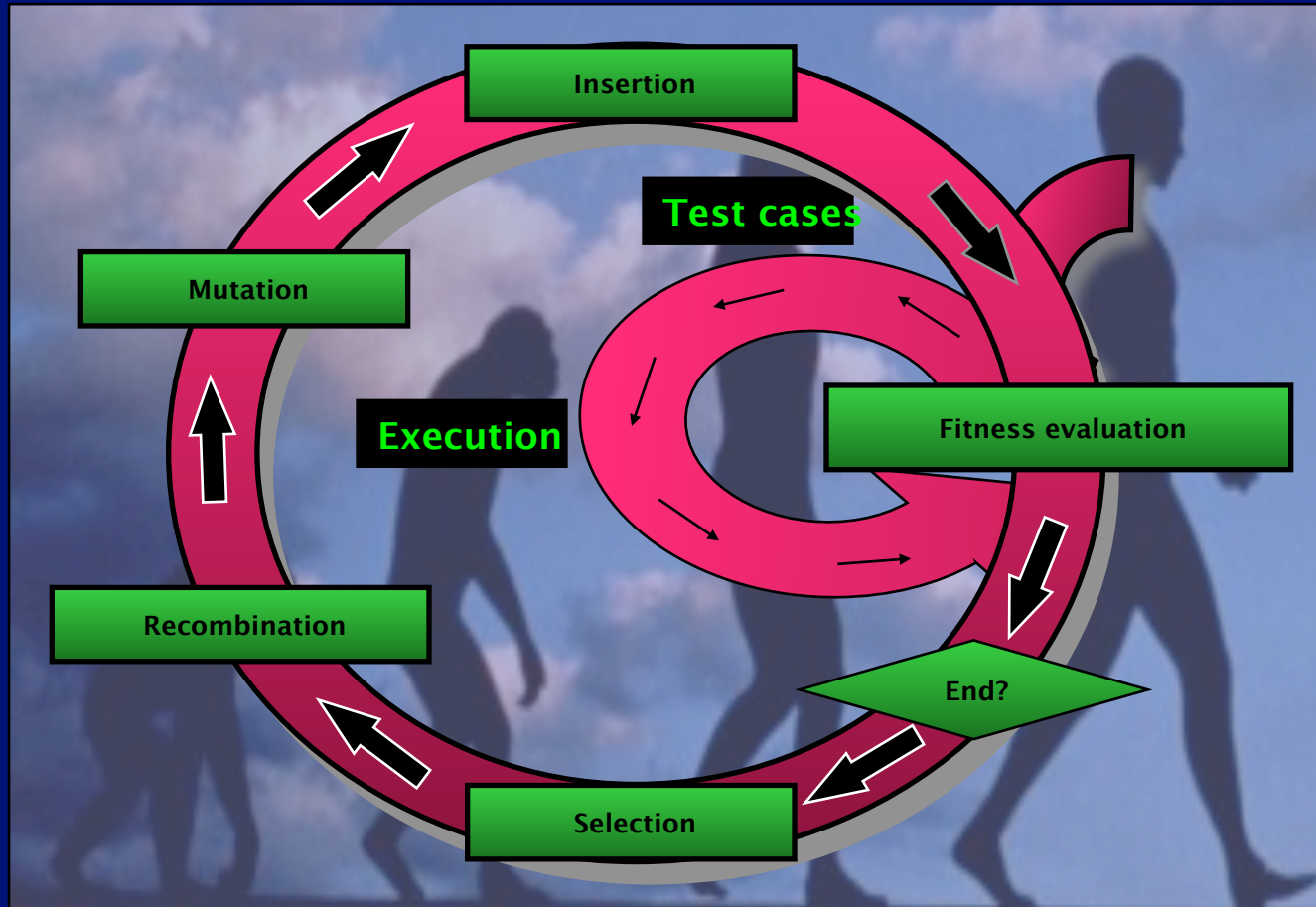
Evolutionary Algorithms



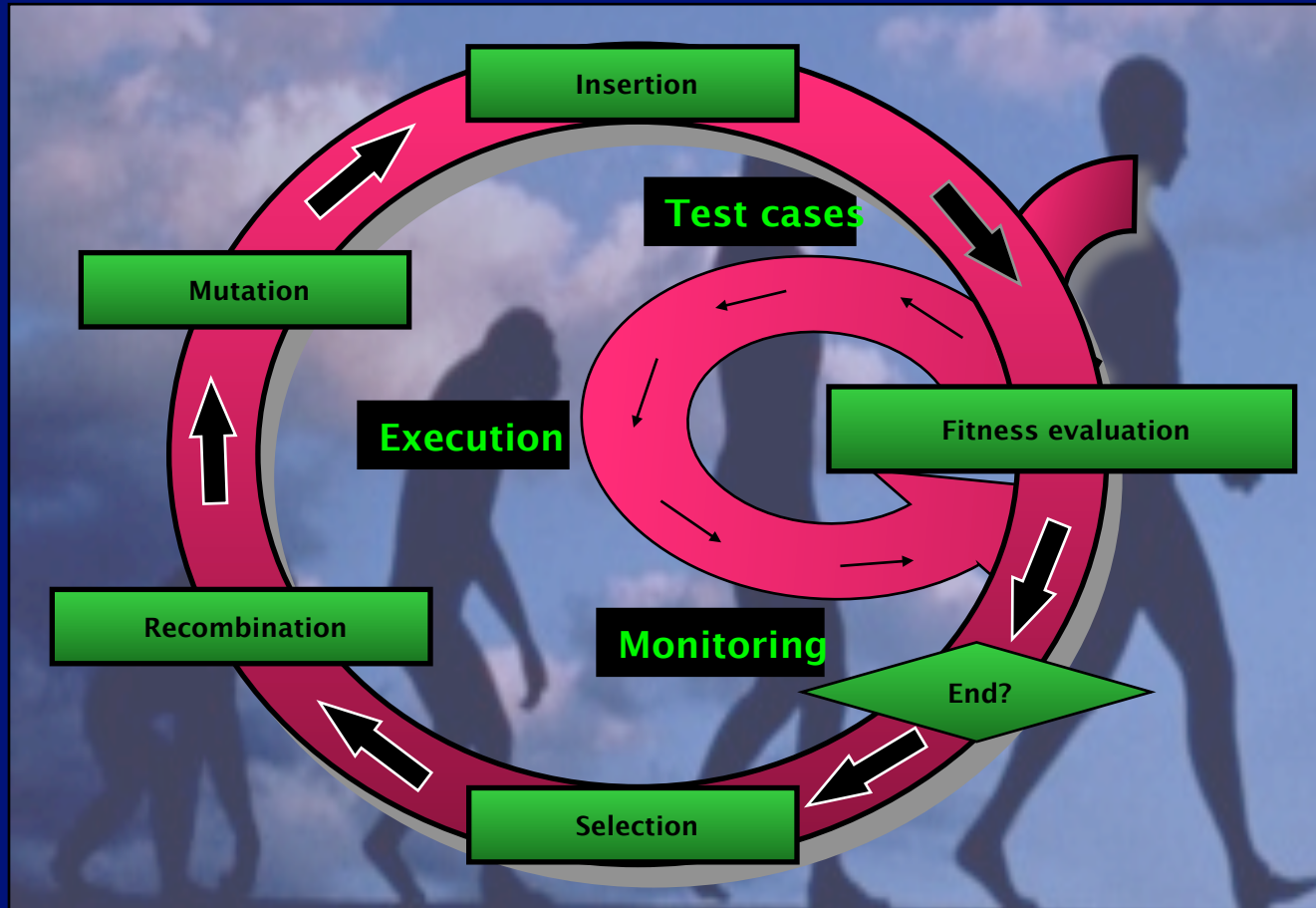
Evolutionary Testing



Evolutionary Testing



Evolutionary Testing



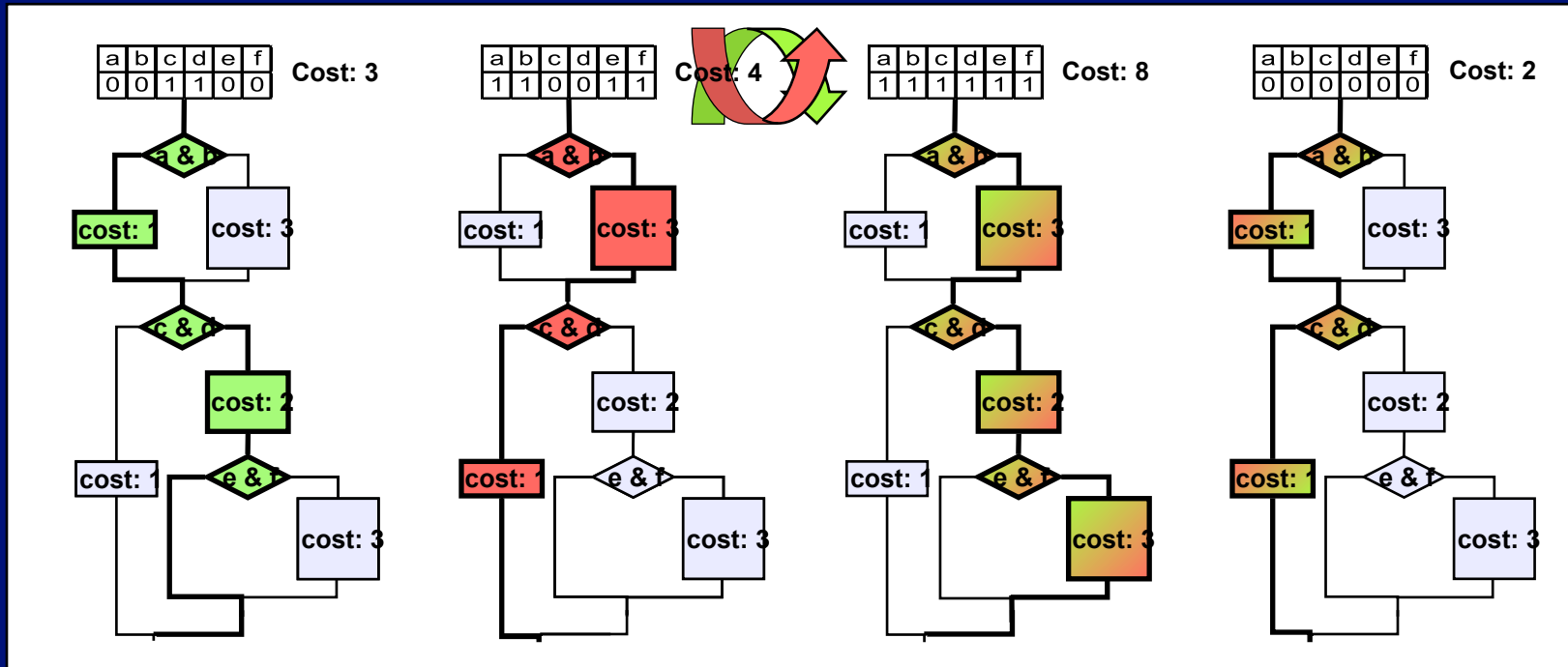
How mating makes life easier

How mating makes life easier

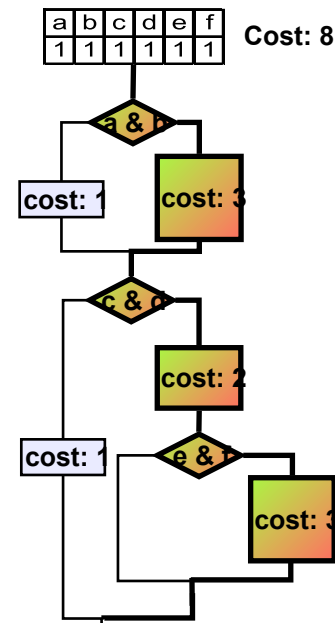
Mating is really very much an analogy
The important property is ***crossover***

How mating makes *life* easier

How mating makes *life* easier

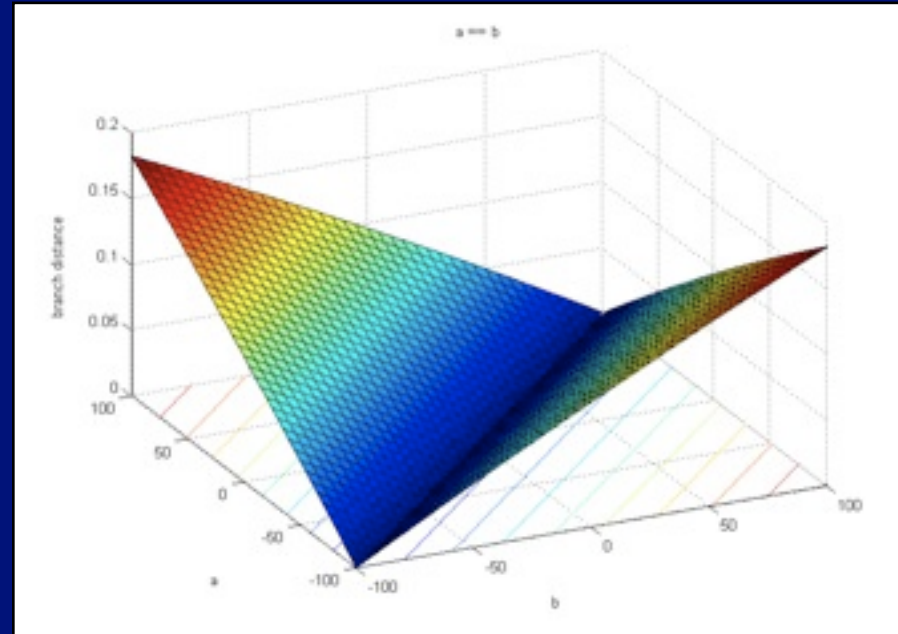


How mating makes *life* easier



Fitness Landscape

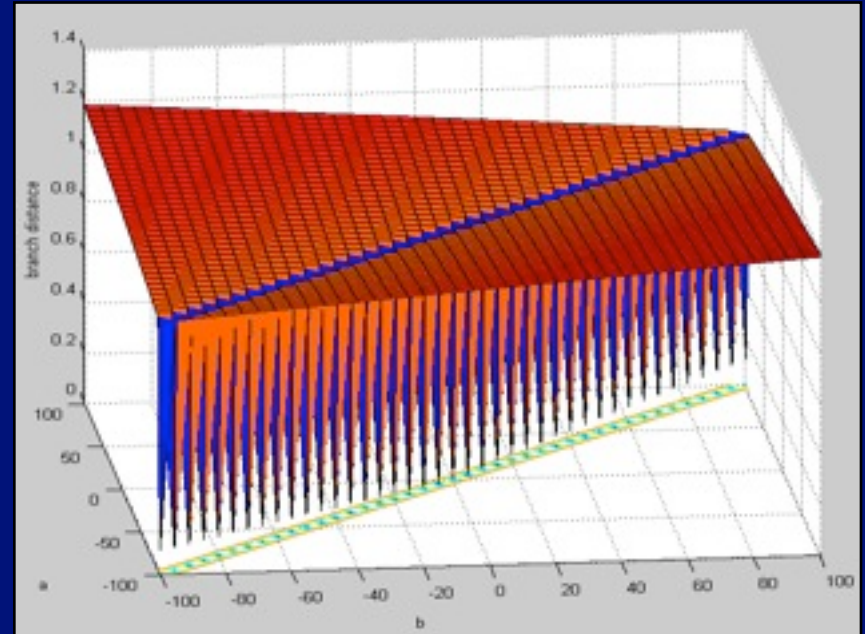
```
void MrNiceGuy(double a, double b)
{
    if (a == b)
    {
        // target 1
        double c = b + 1;
        if (c == 0)
        {
            // target 2
        }
    }
    . . .
}
```



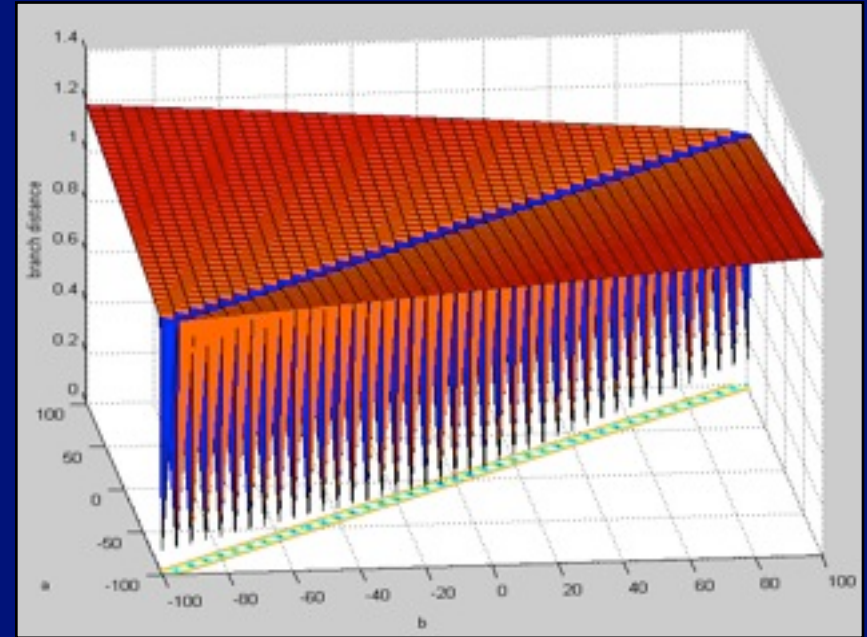
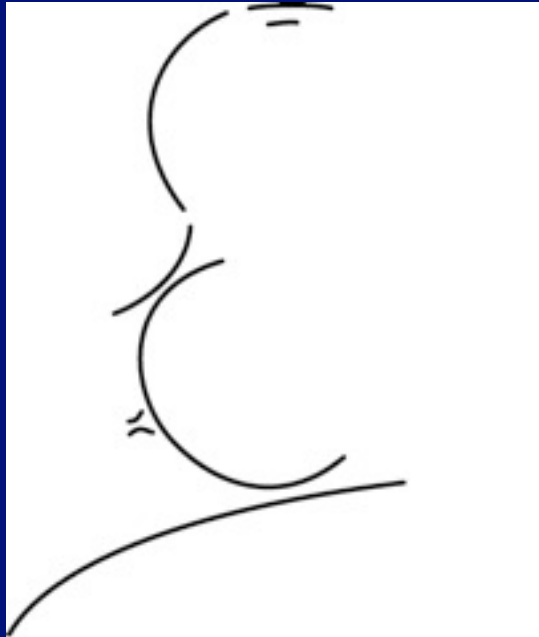
Hitchcock Fitness Landscape

```
void alfred(double a, double b)
{
    if (a == b)
    {
        // target 1
        double c = b + 1;

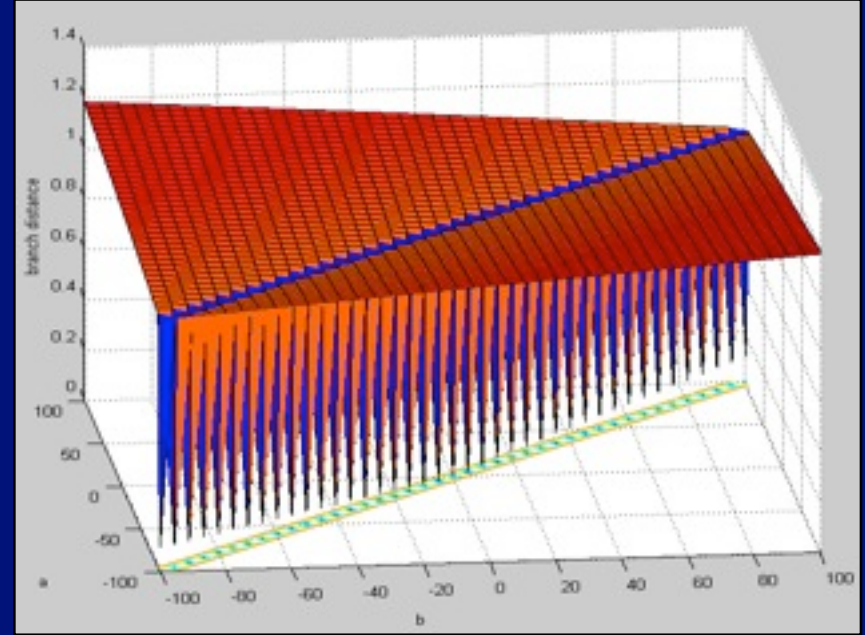
        if (c == 0)
        {
            // target 2
        }
    }
    . . .
}
```



Hitchcock Fitness Landscape



Hitchcock Fitness Landscape



But ...

When does it work

Why does it work (when it does)?

How does it compare to local search?

Schemas

Pop[1] = 010111001010100110010010001

Pop[2] = 101001001010101011111000000

Pop[3] = 010100101010101000001010110

Pop[4] = 010111101010101111110101001

...

Schemas

Pop[1] = 010111001010100110010010001

Pop[2] = 101001001010101011111000000

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...

Schemas

$$\bar{f}(\mathbf{h}, K) = \frac{1}{|\{x \mid x \in \mathbf{h} \wedge x \in K\}|} \sum_{x \in \mathbf{h} \wedge x \in K} f(x)$$

$$N(\mathbf{h}, g+1) \geq N(\mathbf{h}, g) \frac{\bar{f}(\mathbf{h}, P(g))}{\frac{1}{M} \sum_{x \in P(g)} f(x)}$$

$$N(\mathbf{h}, g+1) \geq N(\mathbf{h}, g) \frac{\bar{f}(\mathbf{h}, P(g))}{\frac{1}{M} \sum_{x \in P(g)} f(x)} (1 - p_e \frac{\delta(\mathbf{h})}{\lambda - 1} - p_m o(\mathbf{h}))$$

Schemas

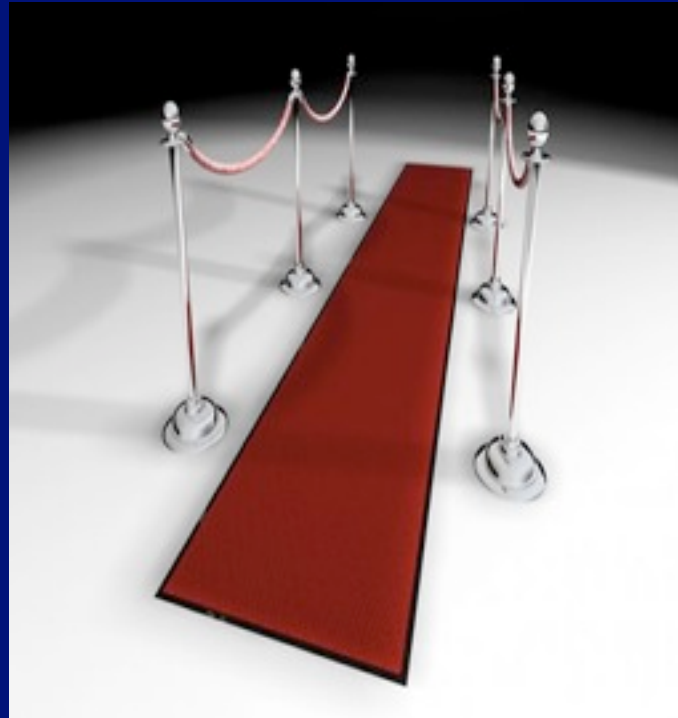
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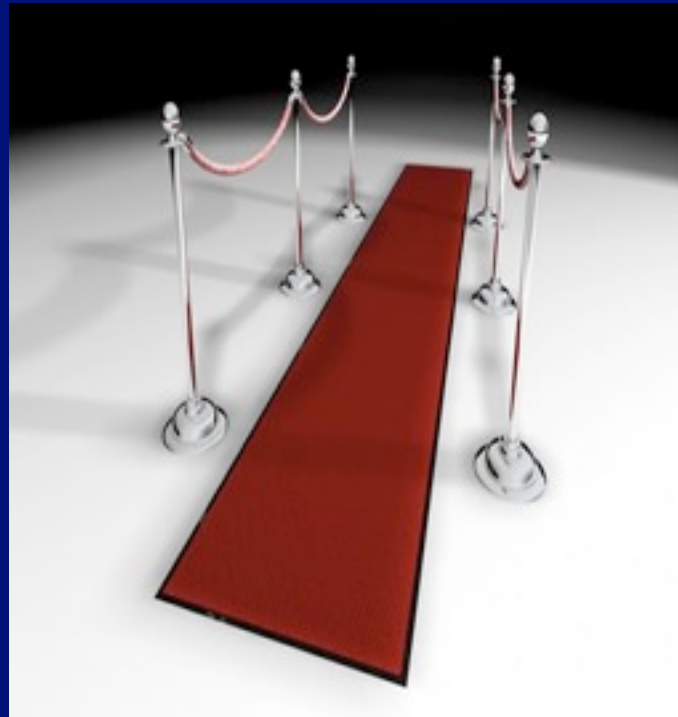
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The Royal Road

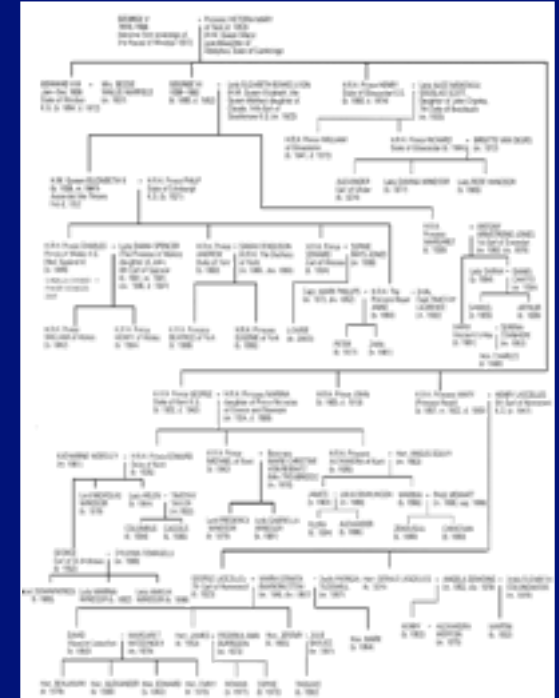
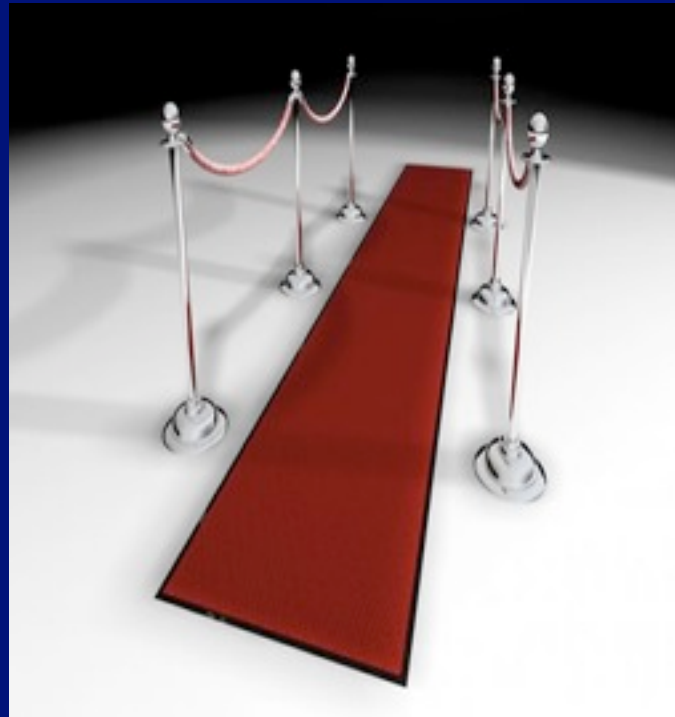
The Royal Road



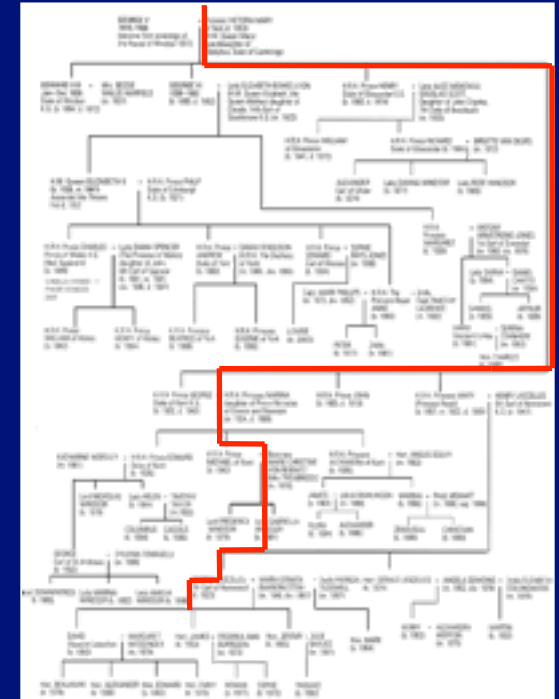
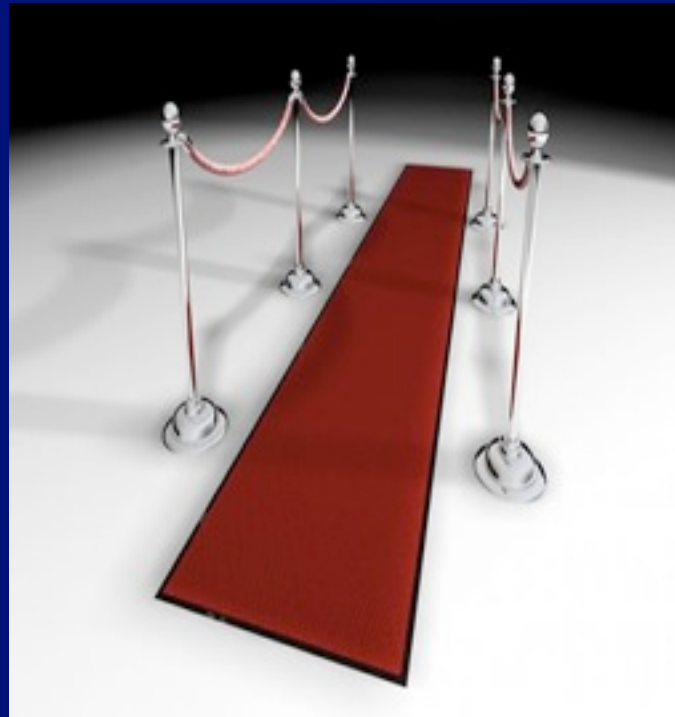
The Royal Road



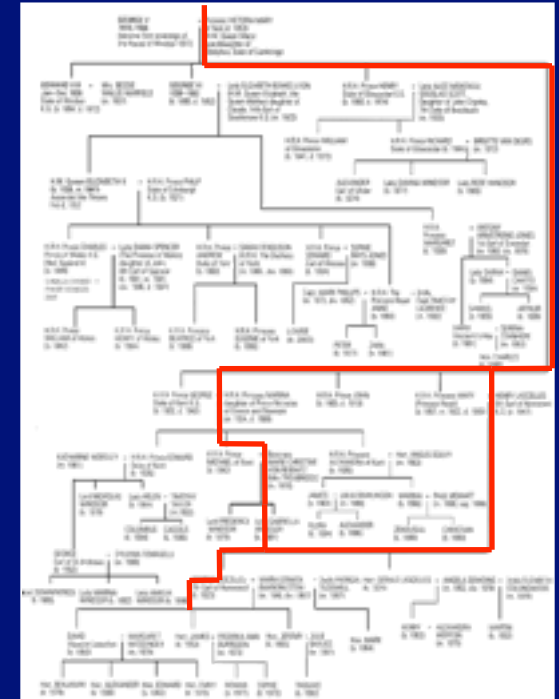
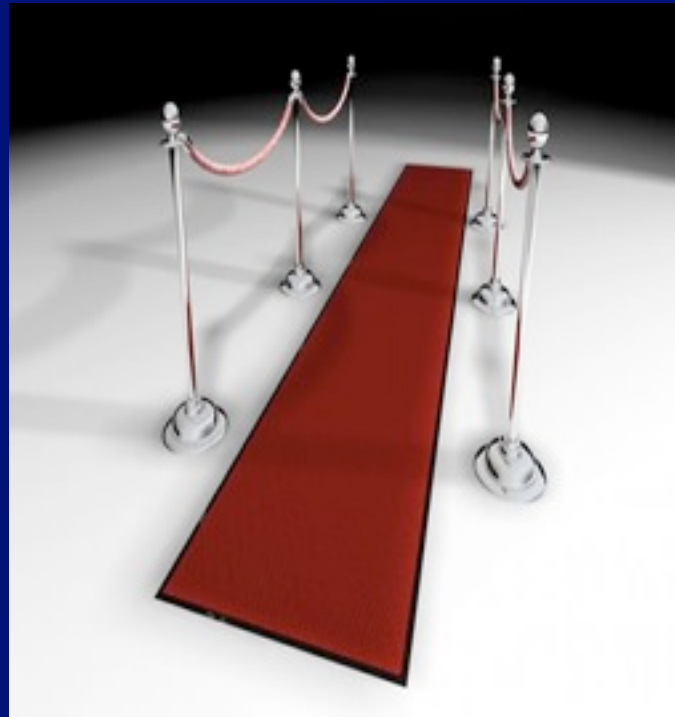
The Royal Road



The Royal Road



The Royal Road



The Royal Road

S1: 1111*****
S2: ****1111*****
S3: *****1111*****
S4: *****1111*****
S5: *****1111*****
S6: *****1111*****
S7: *****1111****
S8: *****1111
S9: 11111111*****
S10: *****1111111*****
S11: *****1111111*****
S12: *****1111111
S13: 11111111111111*****
S14: *****111111111111
S15: 11111111111111111111111111111111



The Royal Road

S1: 1111*****
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S3: *****1111*****
S4: *****1111*****
S5: *****1111*****
S6: *****1111*****
S7: *****1111****
S8: *****1111
S9: 1111111*****
S10: *****1111111*****
S11: *****1111111*****
S12: *****1111111
S13: 11111111111111*****
S14: *****11111111111111
S15: 11111111111111111111111111111111



The Royal Road

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S2: ****1111*****
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S5: *****1111*****
S6: *****1111*****
S7: *****1111****
S8: *****1111
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S10: *****11111111*****
S11: *****11111111*****
S12: *****11111111
S13: 1111111111111111*****
S14: *****1111111111111111
S15: 11111111111111111111111111111111



The Royal Road

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S2: ****1111*****
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S10: *****1111111*****
S11: *****1111111*****
S12: *****11111111
S13: 11111111111111*****
S14: *****11111111111111
S15: 11111111111111111111111111111111



The Royal Road

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S11: *****1111111*****
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S15: 11111111111111111111111111111111



The Royal Road

```
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S7: *****1111****
S8: *****1111
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S10: *****11111111*****
S11: *****11111111*****
S12: *****11111111
S13: 1111111111111111*****
S14: *****11111111111111
S15: 11111111111111111111111111111111
```



Subjects

Bibclean

open source BibTeX pretty printer

Eurocheck

open source € serial number validation

Gimp

open source image manipulation

Spice

analogue circuit simulator

Tiff

TIFF library for image manipulation

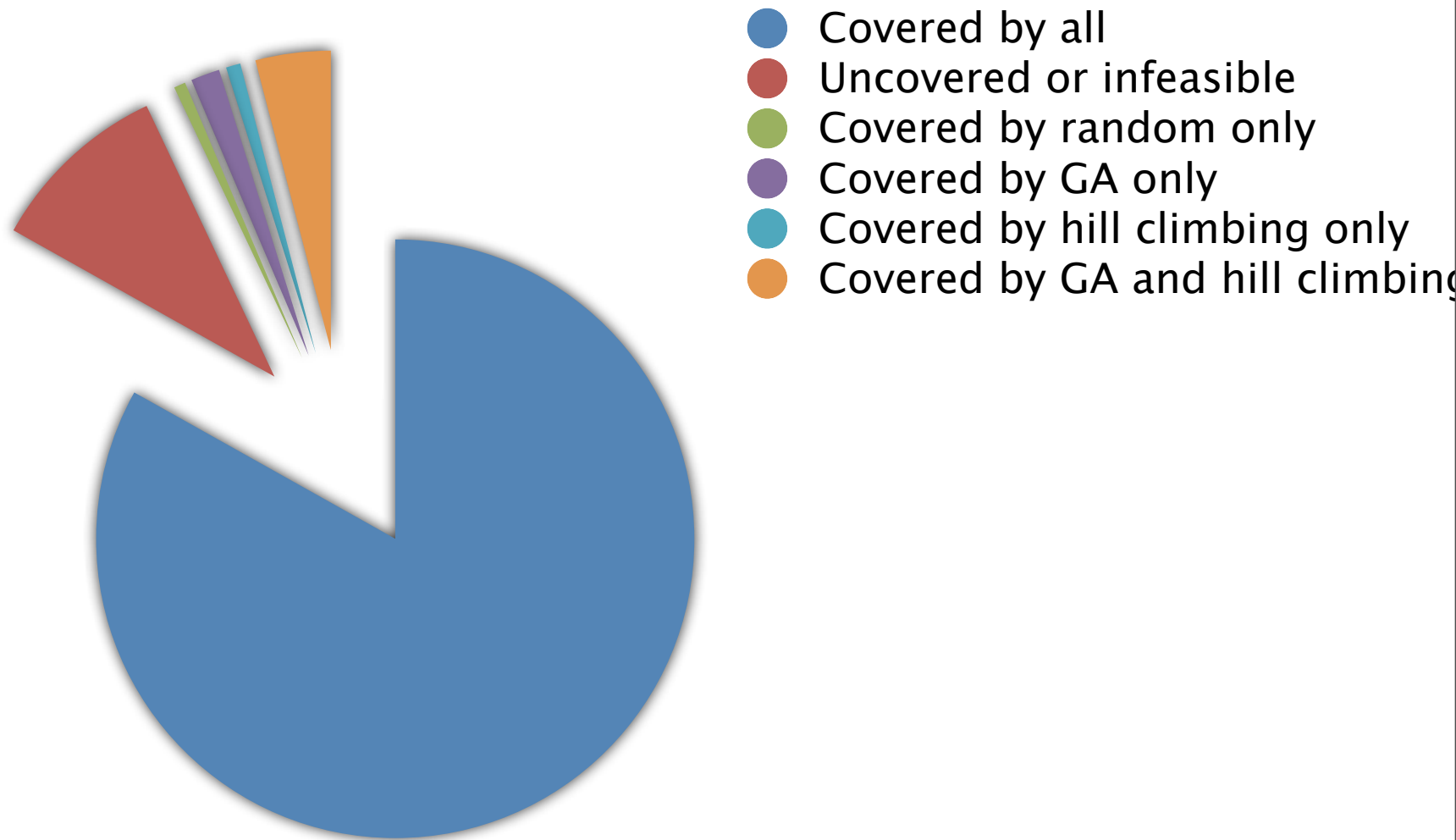
Space

ever heard of this one?

Experimental set up

Fitness evaluations	100,000
Executions	30
Same seeds	for statistical testing

Overall Results



Results

From 640 branches in the six subjects

10 branches

for which Evolutionary Testing was successful
but a simple Hill Climb search was not

5 branches

for which Hill Climbing was successful but
Evolutionary Testing was not

26 branches

Comparability

Royal Roads?

8 branches

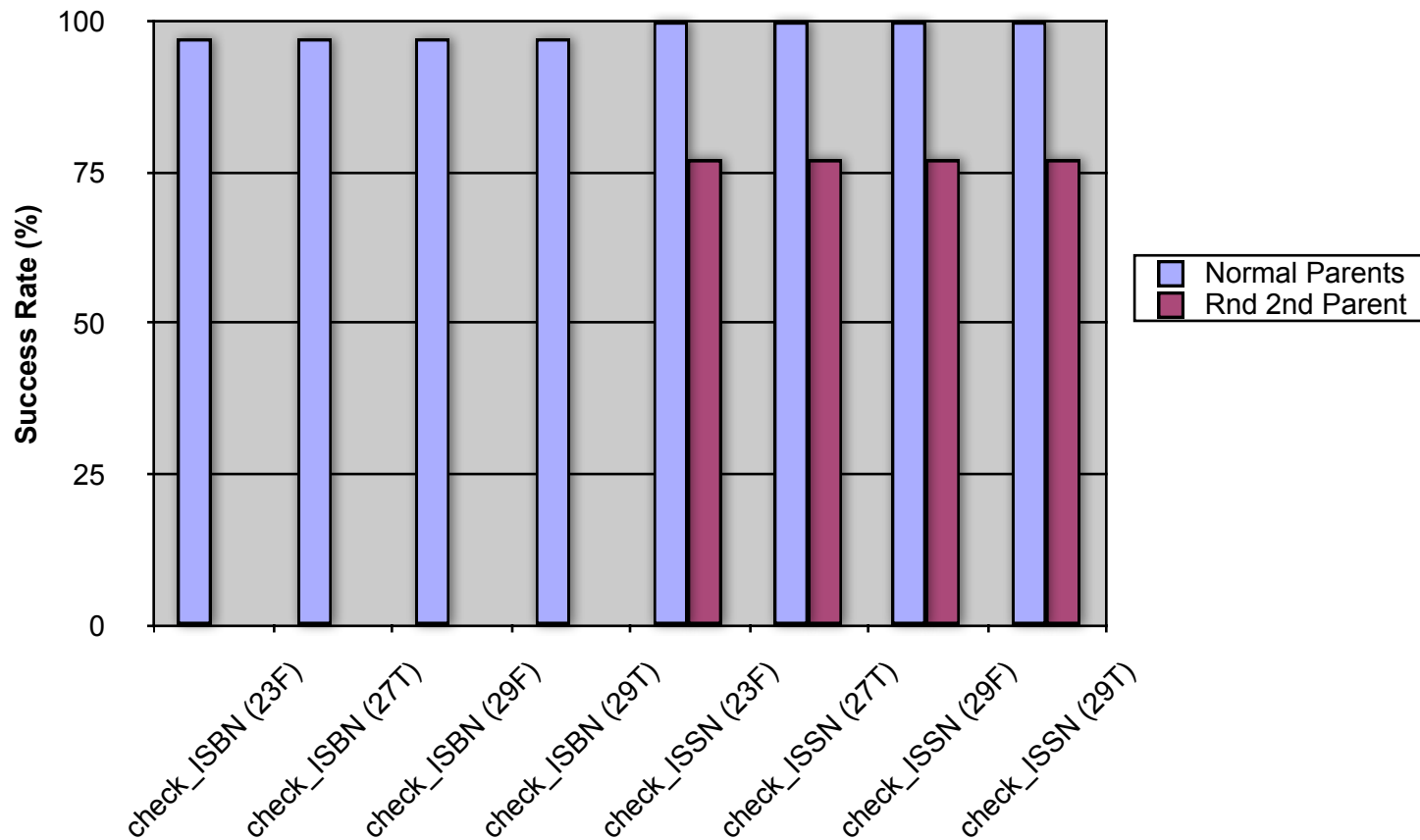
Evolutionary Testing succeeds where Hill Climbing fails:

Branches of the **bibclean** test object

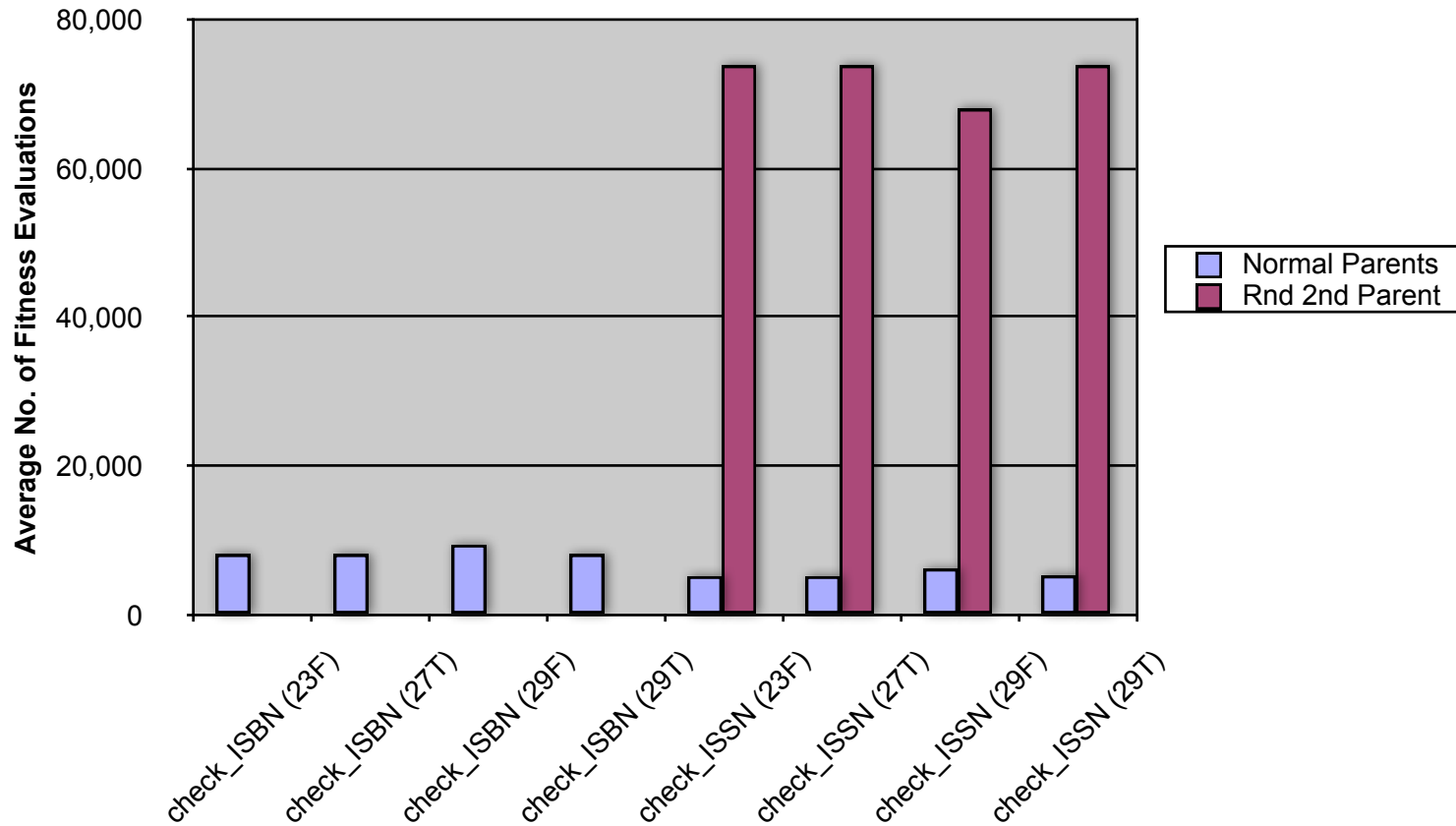
String check for a valid ISBN/ISSN

At least 10 digits

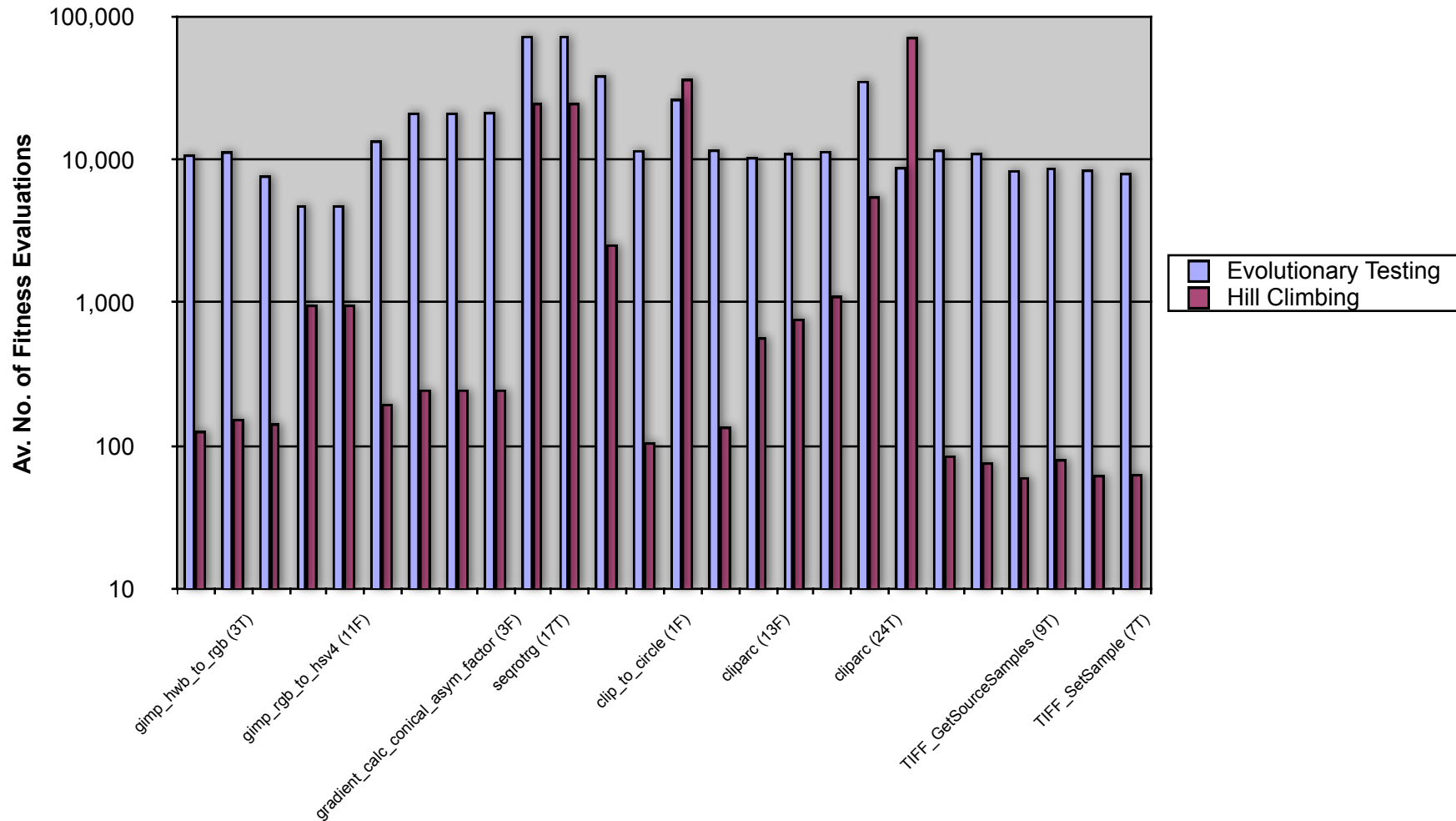
Headless chicken test: success rate



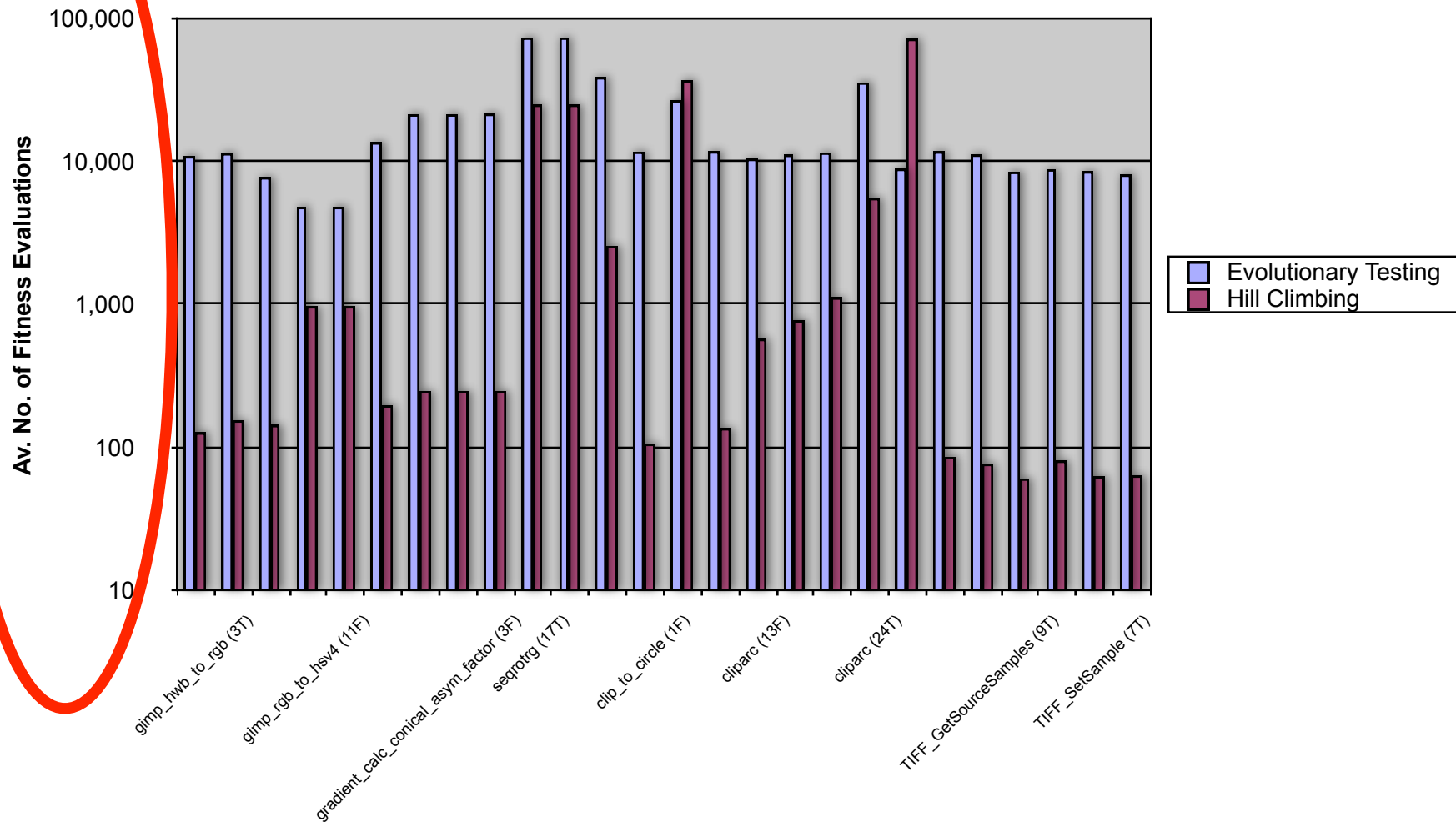
Headless chicken test: test effort



Comparison Local vs Global



Comparison Local vs Global



HC outperforms GA

HC is fast, easy and effective

In 24 of the 26 comparable cases it beats GA

Average speed up is approximately a factor of 20

The results were statistically significant (paired t test)

Conclusions

GA does perform well for Royal Road Functions
... and this is because of the cross over operator

But how many real programs have royal roads?

For those which don't HC is comfortably faster
... by an order of magnitude
... evolution strategies may outperform GA for RR

Of course random covers most branches
... but only the easy ones

Future work

Memetic algorithms

Evolution strategies

Multi objective test data generation

Study of SBT and DART

Other GA theories